WHAT IS CLAIMED IS:

1. A remotely controlled vehicle system, comprising:

a remote control signal transmitter for transmitting control signals;

a master model vehicle containing a remote control signal receiver, wherein said master model vehicle is controlled by said control signals as it travels along a first pathway;

at least one slave model vehicle that is coupled to said master model vehicle and is propelled by said master model vehicle in a pathway outside of said first pathway.

2. The system according to Claim 1, wherein said at least one slave model vehicle is oriented in a formation with said master model vehicle, wherein said at least one slave model vehicle and said master model vehicle move in different pathways while remaining in said formation.

3. The system according to Claim 2, wherein said formation is selectively adjustable by said remote control transmitter.

4. The system according to Claim 1, wherein said at least one slave vehicle is coupled to said master vehicle by at least one linkage element that extends from said master model vehicle at a predetermined angle.

5. The system according to Claim 4, wherein said master model vehicle contains a servo motor that is controlled by said remote control transmitter that selectively adjusts said predetermined angle.

6. The system according to Claim 1, having multiple slave model vehicles, wherein some of said slave model vehicles are interconnected by secondary linkage elements that are not coupled to said master model vehicle.

7. The system according to Claim 1, wherein said master model vehicle and said at least one slave model vehicle are selected from a group consisting of cars, trucks, airplanes, boats and robots.

8. A method of moving a plurality of model vehicles in formation, comprising the steps of:

providing a motor and a control system in a first of said model vehicles, wherein said first of said model vehicles travels along a first pathway;

coupling a remainder of said plurality of model vehicles to said first of said model vehicles, wherein said remainder of said plurality of model vehicles are moved in a formation by said first of said model vehicles along at least one pathway that is adjacent said first pathway.

9. The method according to Claim 8, further including the step of selectively adjusting said formation as said remainder of said plurality of model vehicle are moved by said first of said model vehicles.

10. The method according to Claim 8, wherein said step of providing a motor and a control system in a first of said model vehicles includes providing a remotely controlled model vehicle.

11. The method according to Claim 8, wherein said step of coupling a remainder of said plurality of model vehicles to said first of said model vehicles includes coupling at least some of said remainder of said plurality of model vehicles to said first of said model vehicles with at least one linkage.

12. An assembly, comprising:

a remotely controlled vehicle that moves along a first pathway as directed by remote control signals; and

at least one secondary vehicle coupled to said remotely controlled vehicle that is moved in formation by said remotely controlled vehicle along at least one pathway adjacent said first pathway.

13. The assembly according to Claim 12, wherein said remotely controlled vehicle is coupled to said at least one secondary vehicle by at least one linkage element that extends from said remotely controlled vehicle at a predetermined angle.

14. The assembly according to Claim 13, wherein said predetermined angle can be selectively adjusted by remote control.

15. The assembly according to Claim 12, wherein said remotely controlled vehicle is a car and said at least one secondary vehicle is a car having generally the same shape and appearance as said remotely controlled vehicle.